

United States Patent and Trademark Office



APPLICATION NO	١.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.	
10/642,358	_	08/15/2003	Michael Christopher Burl	EVOL.006A	1624	
20995	7590	03/29/2004		EXAMINER		
		ENS OLSON & F	LAROSE, COLIN M			
	2040 MAIN STREET FOURTEENTH FLOOR IRVINE, CA 92614				PAPER NUMBER	
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				DATE MAILED: 03/29/2004		

Please find below and/or attached an Office communication concerning this application or proceeding.

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• 1	Application No.	Applicant(s)
	10/642,358	BURL ET AL.
Office Action Summary	Examiner	Art Unit
	Colin M. LaRose	2623
The MAILING DATE of this communication app Period for Reply	ears on the cover sheet with the c	orrespondence address
A SHORTENED STATUTORY PERIOD FOR REPLY THE MAILING DATE OF THIS COMMUNICATION. - Extensions of time may be available under the provisions of 37 CFR 1.13 after SIX (6) MONTHS from the mailing date of this communication. - If the period for reply specified above is less than thirty (30) days, a reply If NO period for reply is specified above, the maximum statutory period was reply to reply within the set or extended period for reply will, by statute, Any reply received by the Office later than three months after the mailing earned patent term adjustment. See 37 CFR 1.704(b).	86(a). In no event, however, may a reply be ting within the statutory minimum of thirty (30) day fill apply and will expire SIX (6) MONTHS from cause the application to become ABANDONE	nely filed rs will be considered timely. the mailing date of this communication. D (35 U.S.C. § 133).
Status		
Responsive to communication(s) filed on This action is FINAL . 2b)⊠ This Since this application is in condition for allowant closed in accordance with the practice under <i>E</i> .	action is non-final. ace except for formal matters, pro	
Disposition of Claims		
	election requirement. r. epted or b) objected to by the l	
Applicant may not request that any objection to the objection Replacement drawing sheet(s) including the correction 11) The oath or declaration is objected to by the Expression 11.	on is required if the drawing(s) is ob	jected to. See 37 CFR 1.121(d).
•	ammor. Note the attached emoc	7.0.1011 01 101111 1 1 1 1 1 2 1 1 2 1
Priority under 35 U.S.C. § 119 12) Acknowledgment is made of a claim for foreign a) All b) Some * c) None of: 1. Certified copies of the priority documents 2. Certified copies of the priority documents 3. Copies of the certified copies of the priori application from the International Bureau * See the attached detailed Office action for a list of	s have been received. s have been received in Applicati ity documents have been receive (PCT Rule 17.2(a)).	on No ed in this National Stage
Attachment(s) 1) Notice of References Cited (PTO-892) 2) Notice of Draftsperson's Patent Drawing Review (PTO-948) 3) Information Disclosure Statement(s) (PTO-1449 or PTO/SB/08) Paper No(s)/Mail Date 23 December 2003.	4) Interview Summary Paper No(s)/Mail Da 5) Notice of Informal P 6) Other:	

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DETAILED ACTION

Claim Rejections - 35 USC § 103

- 1. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:
 - (a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negatived by the manner in which the invention was made.
- 2. This application currently names joint inventors. In considering patentability of the claims under 35 U.S.C. 103(a), the examiner presumes that the subject matter of the various claims was commonly owned at the time any inventions covered therein were made absent any evidence to the contrary. Applicant is advised of the obligation under 37 CFR 1.56 to point out the inventor and invention dates of each claim that was not commonly owned at the time a later invention was made in order for the examiner to consider the applicability of 35 U.S.C. 103(c) and potential 35 U.S.C. 102(e), (f) or (g) prior art under 35 U.S.C. 103(a).
- 3. Claims 19-25 and 50 are rejected under 35 U.S.C. 103(a) as being unpatentable over U.S. Patent 5,109,425 by Lawton in view of U.S. Patent 5,838,828 by Mizuki et al. ("Mizuki").

Regarding claims 19 and 50, Lawton discloses a method/circuit for determining a motional state of a mobile robot, the method comprising:

receiving pixel data for video images, where the video images are taken from a camera mounted to the mobile robot (column 1, lines 17-20 and camera 24, figure 5);

processing the pixel data for the video image to identify amounts of spatial gradient within a video image (column 1, lines 25-32: computational means for calculating spatial gradients of the images); and

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comparing the amounts of spatial gradient of a first image to the amounts of spatial gradients of a second video image to detect the motional state of the mobile robot (column 1, lines 32-39: temporal gradient between two images is computed and then used to determine the movement of objects in the field of view, thereby ascertaining the movement of the mobile robot).

Lawton does not disclose characterizing the pixels into two groups corresponding to higher and lower spatial gradients and then using the characterization of the pixels for comparing two different video images.

Mizuki discloses a process, similar to that of Lawton, for determining the presence of motion in a video image. In particular, Mizuki discloses calculating the amounts of spatial gradient of two video images (e.g. via a Sobel filter) and then characterizing the pixels of the image into two groups based on the amount of spatial gradient for each pixel. This results in a "binary edge bit map" whereby each pixel is assigned a value of 1 or 0 based on the amount of spatial gradient (i.e. whether an edge is present). Column 6, lines 12-26.

After characterizing each pixel according to the spatial gradient, the resulting binary edge bit maps are compared to determine the temporal gradients, which provide a measure of movement between corresponding objects in each of the two images. Column 6, lines 27-48.

Thus, Mizuki and Lawton both disclose similar processes for determining the presence of motion in successive video images: calculate the spatial gradient followed by the temporal gradient. Mizuki teaches the additional step of binarizing the spatial gradient calculation prior to the temporal gradient calculation. This extra binarizing step reduces the complexity of the temporal comparison – only single bits are compared for each pixel rather than eight or more –

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and achieves substantially the same results as Lawton's process in that the motion of objects within successive video frames is calculated. For these reasons, it would have been obvious to one skilled in the art to modify Lawton by Mizuki to characterize the pixels as claimed (i.e. binarize the pixels) and then use the binary representation of the pixels for the subsequent (temporal) comparison.

Regarding claim 20, Mizuno discloses arranging the pixels into a binary bit map as claimed.

Regarding claim 21, Mizuno discloses the characterizing comprises comparing a binary value for one pixel of the first image to a group of binary values for pixels of the second image, wherein the group includes a pixel in the same location as the one pixel from the first image (column 8, lines 41-49 and figure 6: for computing distortion values for the motion measurements, the pixels of a present frame and compared to multiple pixels within a search window of a reference frame).

Regarding claim 22, Mizuno discloses computing XOR values between the binary value and the groups of values (column 10, lines 34-42).

Regarding claim 23, Mizuno discloses inspecting pixel data to evaluate whether enough useful spatial gradients exist for robust detection of the motional state (114, figure 5A: there must be enough edges present in order to determine the motion information); and

inhibiting a motional state of "not moving" at least partly in response to a determination that the detection of the motional state is not likely to be reliable (124, figure 5B: if it is

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determined that the motional state measurement is not reliable (i.e. there is high distortion), then the image portion is not assigned a motion vector and no movement is assumed).

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Regarding claim 24, Lawton discloses the motional state is determined only by analysis of visual data observed by the camera 24 (i.e. there are no other types of sensors or the like for collecting data for determining motion).

Regarding claim 25, Lawton's robot is autonomous (figure 5: planetary rover) and the method is performed entirely within the robot (figure 5: machine vision system is contained in the robot).

4. Claim 26 rejected under 35 U.S.C. 103(a) as being unpatentable over Lawton in view of Mizuki as applied to claim 19 above, and further in view of U.s. Patent Application Publication 2004/0017937 by Silverstein.

Regarding claim 26, Lawton discloses all of the image processing is performed within the mobile robot. Lawton is silent to sending, performing, and receiving, as claimed.

Silverstein discloses a mobile robot that relies on image information for navigation control. In particular, Silverstein discloses that image analysis may be performed within the robot, or alternatively, image data may be transferred to a remote processor for analysis (paragraph 39).

It would have been obvious to one skilled in the art to modify Lawton and Mizuki by
Silverstein to send image data to a remote computer, perform part of the pixel characterizing
operations in the remote computer, and then receive an indication of movement from the remote

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computer, since Silverstein shows that image analysis for purposes of determining the motional state of a robot is equivalently performed at remote locations rather than within the robot.

Allowable Subject Matter

5. Claims 1-18, 27-49, 51, and 52 are allowed.

Regarding claim 1, the combination of Lawton and Mizuki teaches all of the claimed features except using the comparison to count the number of pixel identified as unchanged, comparing the count to a threshold, and determining the motional state partly in response to the count.

Regarding claims 27, 45, 49, 51, and 52, Lawton's disclosure is directed towards determining the motional state of a robot, but does not disclose the concept of comparing the actual motional state to an intended motional state in order to change the behavior of the robot.

Conclusion

- 6. The prior art made of record and not relied upon is considered pertinent to applicant's disclosure.
 - U.S. Patent Application Publication 2003/0007682 by Koshizen et al.
 - U.S. Patent 4,628,453 by Kamejima et al.
 - U.S. Patent 4,969,036 by Bhanu et al.
 - "A Structure-from-motion Algorithm for Robot Vehicle Guidance" by Wang et al.

Any inquiry concerning this communication or earlier communications from the examiner should be directed to Colin M. LaRose whose telephone number is (703) 306-3489. The examiner can normally be reached Monday through Thursday from 8:00 to 5:30. The examiner can also be reached on alternate Fridays.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Amelia Au, can be reached on (703) 308-6604. The fax phone number for the organization where this application or proceeding is assigned is (703) 872-9306.

Any inquiry of a general nature or relating to the status of this application or proceeding should be directed to the TC 2600 Customer Service Office whose telephone number is (703) 306-0377.

AMÉLIÀ M. AU SUPERVISORY PATENT EXAMINER TECHNOLOGY CENTER 2600

CML

Group Art Unit 2623

19 March 2004